

## ON ONE METHOD FOR SOLVING DEGENERATING PARABOLIC SYSTEMS BY THE DIRECT LINE METHOD WITH AN APPENDIX IN THE THEORY OF FILTRATION

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Article history:	Abstract:
<p><b>Received:</b> April 20<sup>th</sup> 2021</p> <p><b>Accepted:</b> April 26<sup>th</sup> 2021</p> <p><b>Published:</b> May 31<sup>th</sup> 2021</p>	<p>In this article, we will study the problem arising in the study of the processes of diffusion or filtration of a liquid (gas) in multilayer layers, taking into account convective transfer</p>
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In this article, we will study the problem arising in the study of the processes of diffusion or filtration of a liquid (gas) in multilayer layers, taking into account convective transfer [1,2,3].

In the case of a 3-layer reservoir, the problem is formulated as follows:

Define in

$$\bar{D} = \{0 \leq x \leq 1, 0 \leq z \leq 1, 0 \leq t \leq T\} \text{ u } D_1 = \{0 \leq x \leq 1, 0 \leq t \leq T\}$$

Correspondingly, continuous functions  $u(x, t), u_1(x, z, t), u_2(x, z, t)$  satisfying the system of equations:

$$\begin{cases} \frac{1}{m(x)} \frac{\partial}{\partial x} (k(x) \frac{\partial u}{\partial x}) = A(x, t) \frac{\partial u}{\partial t} + B(x, t) K(x) \frac{\partial u}{\partial x} + \sum_{i=1}^2 A_i(x) K_i(z) \frac{\partial u_i}{\partial z} \Big|_{z=1} + f(x, t, u) + \int_0^t R(t, s) u(x, s) ds \\ \frac{1}{m_i(z)} \frac{\partial}{\partial z} (K_i(z) \frac{\partial u_i}{\partial z}) = A_i(z, t) \frac{\partial u_i}{\partial t} + f(x, z, t, u_i) \end{cases} \quad (1)$$

initial conditions  $u(x, 0) = \varphi(x), u_i(x, z, 0) = \varphi_i(x, z)$  (2) and boundary conditions

$$\begin{cases} (K(x) \frac{\partial u}{\partial x} - a_1(t)u) \Big|_{x=0} = 0 \\ (K(x) \frac{\partial u}{\partial x} + a_2(t)u) \Big|_{x=1} = 0 \\ (K_2(z) \frac{\partial u_2}{\partial z} - a_{12}(t)u_i) \Big|_{z=0} = 0, \\ u(x, t) = u_i(x, 1, t), \quad i = 1, 2 \end{cases} \quad \text{ec.u} \int_0^1 \frac{dz}{K_i(z)} < +\infty \quad (3)$$

Here

$F(x, t, u), F_i(x, z, t, u_i), \varphi(x), \varphi_i(x, z), K(x), m(x), K_i(x), A(x, t), A_i(z, t), B(x, t), A_2(x), a_k(t), (k = 1, 2), R(t, s) a_{12}(t)$  given functions, and

$K(x), m(x) > 0, A(x, t) \geq A > 0, A_i(z, t) \geq A_{i0} > 0, A_i(x) > 0, K_i(0) = 0, K_i(z) \text{ u } m_i(z)$  - positive for  $z \rightarrow 0$ .

We will assume that the solutions themselves and all known functions in the equations are smooth

If a  $\int_0^1 \frac{dz}{K_i(z)} = +\infty$ ,  $\int_0^z \frac{m_i(\xi)d\xi}{K_2(z)} < +\infty$ , then the condition  $(K_i(z) \frac{\partial u_1}{\partial z} - a_{12}(t)u_i)|_{z=0} = 0$  is replaced by the condition  $|u_i(x, z, t)|_{z=0} < +\infty, i = 1, 2$ .

The peculiarity of these problems is that the desired function enters the equations of the problem in such a way that each of the equations has a "Main" unknown function, while the rest are either not contained or are represented by their own boundary conditions.

Introducing division  $t_j = j\tau, j = 0, 1; N = \left[ \frac{T}{\tau} \right]$  we will look for an approximate solution  $\{u_j(x) u u_{ij}(x, z)\}$  using

Rote schemes

$$\begin{cases} Lu_j = A(x, t_j)\delta_\tau u_j + B(x, t_j)K(x) \frac{du_j}{dx} + \sum_{i=1}^2 A_i(x)K_i(z) \frac{\partial u_{ij}}{\partial z} \Big|_{z=1} + f(x, t_j, u_{j-1}) + \tau \sum_{i=0}^{j-1} R_{j,i} u_i \\ L_z u_{ij} = A_i(z, t_j)\delta_\tau u_{ij} + f_i(x, z, t_j, u_{ij-1}) \end{cases} \quad (3)$$

$$u_0(x) = \varphi(x), u_{i0}(x, z) = \varphi_i(x, z), i = 1, 2$$

$$\left| \bar{K}(x) \frac{dv_j}{dx} - a_1(t_j)u_j \right|_{x=0} = 0, \left( K(x) \frac{du_j}{dx} + a_2(t_j)u_j \right) \Big|_{x=1} = 0$$

$$\left( K_i(z) \frac{\partial u_{ij}}{\partial z} - a_{12}(t_j)u_{ij} \right) \Big|_{z=0} = 0, u_{ij}(x, z) = u_j(x) \quad (4)$$

where  $\delta_\tau U_j = \frac{U_j - U_{j-1}}{\tau}, Lu_j = \frac{d}{m(x)} \frac{d}{dx} (K(x) \frac{dU_j}{dx}), l_z u_{ij} = \frac{1}{m_i(z)} \frac{\partial}{\partial z} (k(z) \frac{\partial u_{ij}}{\partial z})$

task for  $j$  everyone (3) (4)- linearly relative  $\{u_j(x), u_{ij}(x, z)\}$  and has the only solution[1,2,3]. Introducing the norm  $\|u\|_j \leq \max_{1 \leq k \leq i} \|u_k\| u \|\cdot\| = \max \|\cdot\|$  according to the maximum principle, the evaluation [2]

$$\left\{ \|u_j\|, \|u_{ij}\| \right\} \leq \max \left\{ \left\| \frac{A(x, t_j)}{\tau} u_{j-1} + f(x, t_j, u_{j-1}) + \tau \sum_{i=1}^{j-1} R_{j,i} u_i \right\|, \max \left\| \frac{A(z, t_j)}{\tau} u_{ij-1} + f(x, z, t_j, u_{j-1}) \right\| \right\} \text{ from here}$$

$$\left\{ \|u_j\|; \|u_{ij}\| \right\} \leq (1 + c_2 T \tau) \max \{ \|u_j\|; \|u_i\| \} + c_1 \tau.$$

By induction

$$\left\{ \|u_j\|; \|u_{ij}\| \right\} \leq \max \{ \|\varphi(x)\|; \|\varphi_i(x, z)\| \} e^{c_2 T^2} + \frac{c_1}{T c_2} (e^{c_2 T^2} - 1)$$

$c_1, c_2$  – some constants depend on input functions.

Functions  $\Phi_j = \delta_\tau u_j, \Phi_{ij}(x, t) = \delta_\tau u_{ij}$  satisfy the system of equations of type a (3), (4).

For solutions  $\Phi_j(x) u \Phi_{ij}(x, t)$  by induction we uniformly estimate

$$\left\{ \|\Phi_j\|, \|\Phi_{ij}\| \right\} \leq c_3 \exp(c_4 T) + c_3 \frac{\exp(c_4 T) - 1}{c_4} = M_1$$

In the future, through  $M_k$  we will denote constants depending on the input data of the problems. Let us establish the uniform boundedness of the families of quantities.

$$\left\{ \|u_j\|, \|u_{ij}\| \right\}, \left\{ \|\Phi_j\|, \|\Phi_{ij}\| \right\}, \left\{ \|L\Phi_j\|; \|L_z\Phi_{ij}\| \right\}, \left\{ \|Lu_j\|, \|L_z u_{ij}\| \right\}, \left\{ \|\delta_\tau \delta_\tau u_{j-12}\|; \|\delta_\tau \delta_\tau u_{i,j-1}\| \right\}$$

From the established estimates, we have

$$\left| \frac{du_j}{dx} \right| \leq M_4 \psi(x), \left| \frac{d\Phi}{dx} \right| \leq M_5 \psi(x),$$

$$\left\{ \begin{array}{l} \left| \frac{du_{ij}}{dz} \right| \leq M_6 \psi_i(z), \\ \left| \frac{d\Phi_{ij}}{dz} \right| \leq M_7 \psi_i(z) \end{array} \right., \quad z > 0 \quad (6)$$

Where  $\psi(x) = \frac{\int_0^x m(\xi) d\xi}{K(x)}$  - uniformly bounded function. And for the function  $\psi_i(x) = \frac{\int_0^z m_i(s) ds}{K_i(z)}$  consider the

following cases:

Case 1. Limit  $\overline{\lim}_{z \rightarrow 0} \psi(z)$  finite. Then the right-hand side of (6) is bounded by a constant that does not depend on the partitioning method. In the limit  $\tau \rightarrow 0$  linear interpolations  $u^\tau(x, t)$  and  $u_i^\tau(x, z, t)$  accordingly in  $D$  and  $D_1$  coinciding with  $u(x, j\tau)$  and  $u_i(x, z, j\tau)$  at  $t = j\tau$  and linearly depending on  $t$  inside the layers  $j\tau \leq t \leq (j+1)\tau$  give a solution  $u(x, t)$  and  $u_i(x, z, t)$ ,  $i = 1, 2$  in area  $D$  and  $D_1$  respectively

Case 2. If  $\overline{\lim}_{z \rightarrow +\infty} \psi_i(z)$  is infinite or does not exist, then we cannot use estimate (6) to prove the equicontinuity of families. However, using the boundary conditions at  $z=0$ , one can be convinced of the equicontinuity of the families in this case as well.

**Note 1**

For the numerical solution, a modified version of the differential sweep is used [2] and is implemented by the Maple software system

**Note 2**

The approximate solution constructed by the method of lines converges to the exact one with the speed  $o(\tau)$ ,  $\tau$  - time step

**LITERATURE**

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